

SOLUTIONS

CIRCULAR MOTION

1. $(\theta) = 2t^3 + 0.5$

$$\omega = \frac{d\theta}{dt} = 6t^2$$

at $t = 2$ s

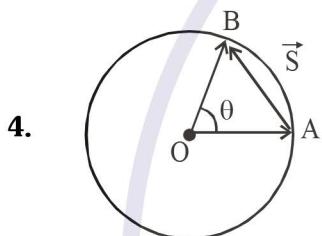
$$\omega = 6 \times 4 = 24 \text{ rad/s}$$

2. $\omega = \frac{\Delta\theta}{\Delta t} \Rightarrow \omega = \frac{2\pi}{60} = \frac{\pi}{30} \text{ rad/s}$

3. $\vec{v} = \vec{\omega} \times \vec{r}$

$$\vec{v} = \begin{vmatrix} i & j & k \\ 3 & -4 & 1 \\ 5 & -6 & 6 \end{vmatrix}$$

$$\vec{v} = -18\hat{i} - 13\hat{j} + 2\hat{k} \text{ m/s}$$



4. $\theta = \omega t$

$$\vec{S} = \overrightarrow{OB} - \overrightarrow{OA}$$

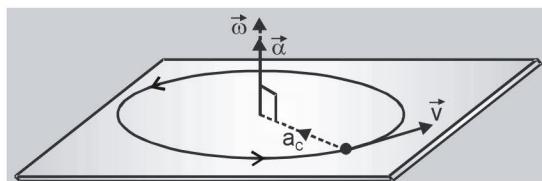
$$S = \sqrt{R^2 + R^2 + 2R^2 \cos(\pi - \omega t)}$$

$$S = 2R \sin\left(\frac{\omega t}{2}\right)$$

5. $a_c = \frac{v^2}{r} = \frac{4}{r^2} \Rightarrow v^2 = \frac{4}{r}$

$$\Rightarrow v = \frac{2}{\sqrt{r}}$$

Momentum $p = mv = \frac{2m}{\sqrt{r}}$



6.

7. $(F_C)_{\text{heavier}} = (F_C)_{\text{lighter}}$

$$\Rightarrow \frac{2mV^2}{r} = \frac{m(nV)^2}{2r} \Rightarrow n^2 = 4 \Rightarrow n = 2$$

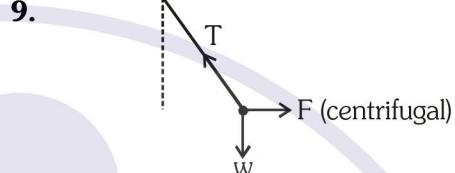
8. Speed is constant

$$a_t = 0$$

$$a_{cp} = \frac{v^2}{r} = \text{constant}$$

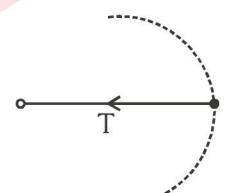
$$|a_{net}| = \text{constant}$$

9.



10. $a_{cp} = \frac{v^2}{R} \Rightarrow a_t = \frac{dv}{dt} = a \Rightarrow a_{net} = \sqrt{a_t^2 + a_{cp}^2}$

11. $f_{net} = \text{centripetal force}$



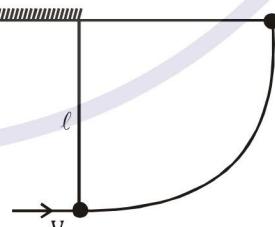
$$T = \frac{mv^2}{r}$$

12. $v = 72 \text{ km/h} \Rightarrow \frac{v^2}{rg} = \tan \theta$

$$v = \frac{72 \times 5}{18} = 20 \text{ m/s} \Rightarrow \tan \theta = \frac{400}{20 \times 10}$$

$$\tan \theta = 2 \Rightarrow \theta = \tan^{-1} 2$$

13.

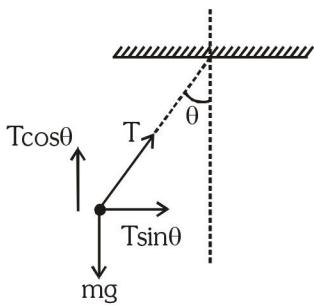


by COME

$$\frac{1}{2}mv^2 = mgl + O \Rightarrow v = \sqrt{2gl}$$

14. Using centre of Mass

$$F_{cp} = m\omega^2 r = \frac{m\omega^2 l}{2}$$



$$Tsin\theta = mv^2/r$$

$$Tcos\theta = mg$$

$$\tan \theta = \frac{v^2}{rg}$$

$$\tan \theta = \frac{100}{10 \times 10} = 1$$

$$\theta = 45^\circ$$

16.

by COME

$$v = \sqrt{2gl \sin \theta}$$

$$a_T = \sqrt{a_{cp}^2 + a_t^2}$$

$$a_{cp} = \frac{v^2}{r} = \frac{2g\ell \sin \theta}{\ell} = 2gs \sin \theta$$

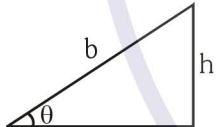
$$\text{and } a_t = g \cos \theta$$

$$a_{net} = \sqrt{(g \cos \theta)^2 + (2g \sin \theta)^2} = g\sqrt{1 + 3 \sin^2 \theta}$$

17. to complete circle

$$v = \sqrt{5gr} \quad \text{by COME} \quad h \geq \frac{5}{2}r$$

18.



$$\therefore \frac{h}{b} = \frac{v^2}{Rg}$$

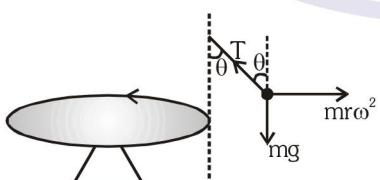
$$\therefore h = \frac{v^2 b}{Rg}$$

$$\tan \theta \approx \sin \theta = \frac{h}{b}$$

19. $T \cos \theta = mg$

$$T \sin \theta = mr\omega^2$$

$$\therefore \tan \theta = \frac{r\omega^2}{g}$$



20. For looping the loop minimum velocity at top point

$$v = \sqrt{gL}$$

time taken by particle

$$t = \sqrt{\frac{2h}{g}} = \sqrt{\frac{2 \times 2L}{g}} = 2\sqrt{\frac{L}{g}}$$

$$\therefore \text{horizontal range } x = vt = \sqrt{gL} \times 2\sqrt{\frac{L}{g}} = 2L$$

$$\tan \theta = \frac{v^2}{rg}$$

by ↑ speed by 10% speed becomes $1.1v$

$$\therefore \frac{v^2}{rg} = \frac{(1.1v)^2}{r'g}$$

$$\therefore r' = (1.1)^2 r = 24.2 \text{ m}$$



angular velocity ω is same for all.

$$T_C = m\omega^2 (3\ell)$$

$$T_B = T_C + m\omega^2 (2\ell) = m\omega^2 (5\ell)$$

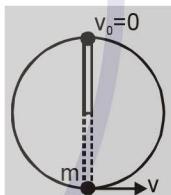
$$T_A = T_B + m\omega^2 (\ell) = m\omega^2 (6\ell)$$

$$\therefore T_C : T_B : T_A :: 3 : 5 : 6$$

23. At top most point speed of the body may be zero, because rod will support the body there

$$\therefore \frac{1}{2}mv^2 = 0 + mg(2\ell)$$

$$v = \sqrt{4gl}$$

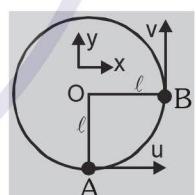


$$24. \bar{v} = v\hat{j} \text{ and } \bar{u} = u\hat{i}$$

By COME between A and B

$$\frac{1}{2}mv^2 + mg\ell = \frac{1}{2}mu^2$$

$$\therefore v = \sqrt{u^2 - 2g\ell}$$



$$\Delta \bar{v} = \bar{v} - \bar{u} = \sqrt{u^2 - 2g\ell} \hat{j} - u\hat{i}$$

$$|\Delta \bar{v}| = \sqrt{(\sqrt{u^2 - 2g\ell})^2 + u^2} = \sqrt{2(u^2 - g\ell)}$$

25. In Balancing condition

$$F_{\text{centrifugal}} \leq \text{Friction force}$$

$$mr\omega^2 \leq \mu mg$$

$$r \leq \frac{\mu g}{\omega^2}$$

$$f_r = F_{CP} = \frac{Mv^2}{R}$$

$$\text{But } f_r \leq \mu Mg$$

$$\text{So } v^2 \leq \mu_s R g$$

$$v_{\max} = \sqrt{\mu_s R g}$$

27. By using work-energy theorem, $W = \Delta KE$

$$\Rightarrow (ma_t) (4\pi R) = \frac{1}{2} mv^2 \Rightarrow a_t = \left(\frac{\frac{1}{2} mv^2}{4\pi m R} \right)$$

$$\Rightarrow a_t = \frac{8 \times 10^{-4}}{4 \times 3.14 \times 10 \times 10^{-3} \times 6.4 \times 10^{-2}} = 0.1 \text{ m/s}^2$$

OR

$$\frac{1}{2} mv^2 = KE \Rightarrow \frac{1}{2} \left(\frac{10}{1000} \right) v^2 = 8 \times 10^{-4}$$

$$\Rightarrow v^2 = 16 \times 10^{-2} \Rightarrow v = 4 \times 10^{-1} = 0.4 \text{ m/s}$$

Now,

$$v^2 = u^2 + 2a_t s \quad (s = 4\pi R)$$

$$\Rightarrow \frac{16}{100} = 0^2 + 2a_t \left(4 \times \frac{22}{7} \times \frac{6.4}{100} \right)$$

$$\Rightarrow a_t = \frac{16}{100} \times \frac{7 \times 100}{8 \times 22 \times 6.4} = 0.1 \text{ m/s}^2$$

28. $\frac{v^2}{rg} = \tan(\phi - \theta)$

$$= \frac{\tan \phi - \tan \theta}{1 - \tan \phi \tan \theta} = (\mu_s = \tan \theta)$$

$$\Rightarrow v = \sqrt{rg \frac{\mu_s - \tan \theta}{1 - \mu_s \tan \theta}} \quad (\mu_s = \tan \phi)$$

OR

Check by dimensions.

29. Centripetal acceleration = $\frac{v^2}{R} = a \cos 30^\circ$

$$\Rightarrow v = \sqrt{aR \cos 30^\circ} = \sqrt{7.5 \times 5 \times \frac{\sqrt{3}}{2}} = 5.7 \text{ m/s}$$